# WHAT'S INSIDE?

H1 2019

## **EXECUTIVE LENS**

Summarized insights for Vision Systems w.r.t. trends in technology, market, and players

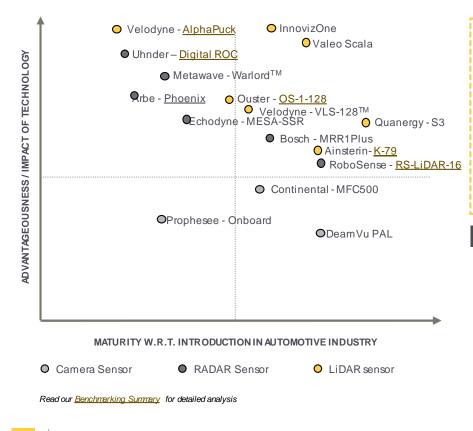


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#### State of the Trend

Vision sensor technology is being enhanced by companies working on higher detection range, enhanced reliability, smaller size and lower cost



- · Many companies are enhancing range and effectiveness of their LiDARs using multiple techniques like surface mount flip chip, FMCW, etc. Read Technology Take-offsfor details
- · Toolslike Alisbeing used by companies to enhance the input from vision sensors like Radar, LiDAR and camera
- · Headlight manufacturer's are betting on partnership to fit vision sensors like LiDAR, Radar, etc. into headlamp assembly
- Some companies are using only cameras with some enhanced detection hardware and sophisticated software for autonomous vehicle, but effectiveness of same in harsh conditions are unknown

#### Key Developments in the past 6 months [echnology tu simple Fechnology **UHNDER** TuSimple demonstrated production quality Uhnder introduces first digital automotive camera system for night driving capabilities RADAR-on-chip Funding Korlo BrightWav Vision gets funding from Headlight RoboSense lidar to equip GACHA bus fleet for Manuf acturer KOITO and Magenta winter conditions

Read Funding Summary for more

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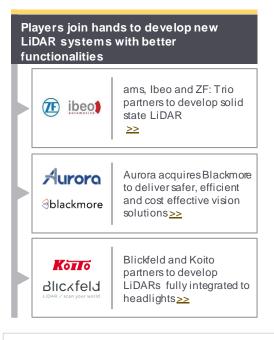


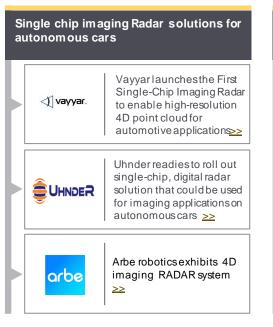
#### **Emerging Trends**

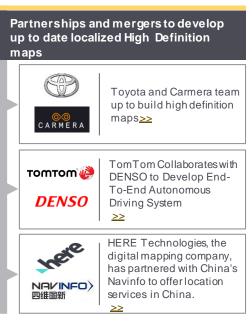
Collaborations in the industry for 'efficient, size and cost optimized LiDARs':

Single chip imaging radar systems from various players;

Partnerships to develop up to date high definition maps;







- More players are partnering to develop efficient and cost effective LiDAR solutions for autonomous systems
- Vehicle component manufactures and LiDAR players made partnership to integrate LiDAR to various automotive components such as headlights, bumpers, windshields etc.
- Developments were made towards the improvement of resolution and size optimization of automotive radars

For more details read our Pulse >>

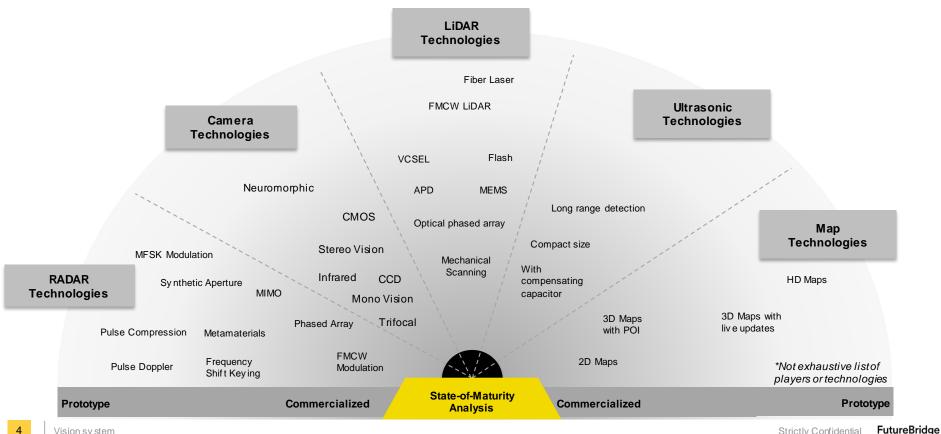
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## **Maturity Fan**

Technologies enabling 3D vision (in Camera), Antenna miniaturization (in Radar) and solid state LiDARs moving faster towards commercialization



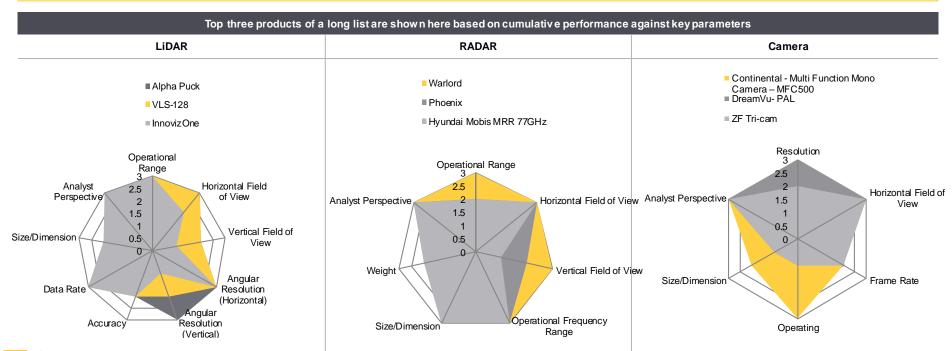




#### **Benchmarking Summary**

Alpha Puck from Velodyne leads in LiDAR, Warlord from Metawave in Radar and MFC500 from continental in cameras

- Alpha Puckby Velodyne is the leading LiDAR followed by Velodyne VLS 128 and then by InnovizOne.
- $\bullet \ \ \text{In case of Radars Warlord} \ is the \ leading \ one \ followed \ by \ Phoenix \ and \ Hyundai \ Mobis \ MRR \ 77.$
- $\bullet \ \ Among \ Cameras \ Continental \ MFC \ 500 \ is the \ best followed \ by \ Dream \ Vu \ and \ then \ by \ ZF \ Tri-cam.$



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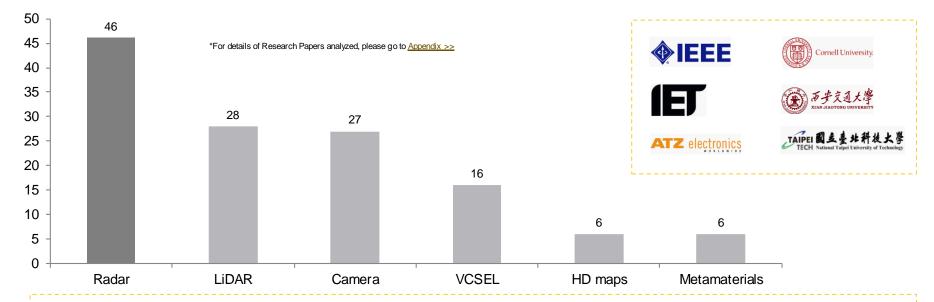
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## Research Activity Summary

Academic research is very active in vision system areas especially in addressing range, cost and detection challenges



- > Many researchers are exploring ways to increase detection capacity of vision sensors by changing frequencies, using Al based software, etc.
- > Combining data from LiDAR, radar and camera whichever are available and putting in HD maps effectively can reduce error of sensing than using data in separation
- > Research points out to effective transfer of data using V2X for enhanced detection range and reduce cost of sensor systems than trying to increasing vision sensor performance after certain limit

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#### **Challenges & Potential Solutions**

CHALLENGES

Software based technological upgrades is solving many challenges of LiDAR and Radar systems

There are many challenges in case of LiDAR and Radar sensor faced by industry.

Researchers are coming up with innovative ideas to reduce cost, improve detection, faster and safer sensor data transfer, etc.

## Unce

LiDAR

**Systems** 

Radar

Systems

Uncertainty estimation of LiDAR matching aided by dynamic vehicle detection and high definition map

## Uncertainty of LiDAR matching(ULM) and aiding higher accuracy >>

- A nov el Uncertainty of LiDAR matching(ULM) is proposed with help of dy namic vehicle detection and HD maps
- Better accuracy compared to conventional Hessian matrix-based approach
- Researchers propose to correlate ULM with detected DV and convergence feature of matching algorithm for calculating ULM

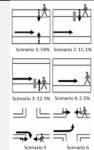




# Pedestrian recognition using micro Doppler effects of radar signals based on machine learning and multi-objective optimization

# A pedestrian detection method using 79 GHz radar ≥≥

- Proposed method aims early detection of pedestrians using micro Doppler characteristics of human body in near to crash situations (0– 15 m)
- It says model involving a polynomial kernel for Support Vector Machine reported better result in terms of accuracy (99.5%)



#### Image-based compression of LiDAR sensor data

## LiDAR data compression makes faster and safer data transfer >>

- A method of compression of LiDAR data for high compression ratio, low computational requiring and least loss of data is explained in research paper
- It proposes conversion of LiDAR data into a 2D image array and using existing image compression method





## High-Density clutter recognition and suppression for automotive Radar systems

# Increasing radar detection capability using clutter recognition and suppression ≥≥

- On the basis of distinctive beat frequency distribution in high-density clutter environment recognition parameter is defined
- Clutter is suppressed using correlation between up-chirp and down-chirp received signals





#### **Challenges & Potential Solutions**

CHALLENGES

Camera driven autonomous vehicle is being heavily researched and HD maps are getting sophisticated

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Camera

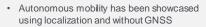
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**HD Maps** 

Many researchers are developing a camera based approach in Autonomous Vehicle to reduce cost significantly and HD map optimization can help in AV localization

## Project AutoVision: localization and 3D scene perception for an autonomous vehicle with a multi-camera system

## Navigating vehicle using multiple cameras >>



 Pilot project used 16 cameras and 4 LiDARs for 3D perception and navigation

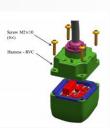




#### Investigation on the Material Failure in a Small Scale Automotive Camera Module via Root Cause Analysis and Experimental Validation

## Camera module material failure analysis ≥≥

- Research paper investigated lens holder material failure using root cause analy sis and experimental validation
- The lens holder structure has optimized af teridentifying structural problem and improved with 35% increase in strength



## Exploiting sparse semantic HD Maps for self-driving vehicle localization

## HD maps for autonomous vehicle localization ≥≥

- Research paper demonstrates a localization system capable of localizing an autonomous vehicle against a map requiring roughly three orders of magnitude less storage than traditional methods
- System has been tested by authors for about 300 km for effectiveness of same





Generation of horizontally curved driving lines in HD Maps using Mobile Laser Scanning Point Clouds

## HD Maps generation using mobile laser scanning ≥≥

- Research paper proposes a semiautomated driving line generation method using point clouds acquired by a mobile laser scanning system
- The generated HD maps using the method explained in research paper can be used in AV for data localization



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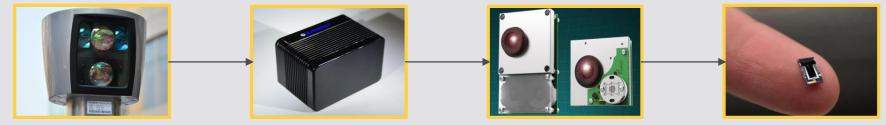


## SoC – Innovations in Vision Sensors driven by need of Miniaturization in Automotive

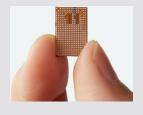
System on Chip technology is making LiDARs and Radars are getting miniaturized even at fractional size of existing ones



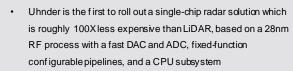
#### Miniaturization in LiDARs



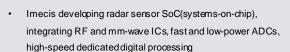
#### Miniaturization in Radars







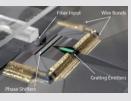




unec

It employs Phase Modulated Continuous Wave (PMWC) for CMOS implementation as it resistant to interference



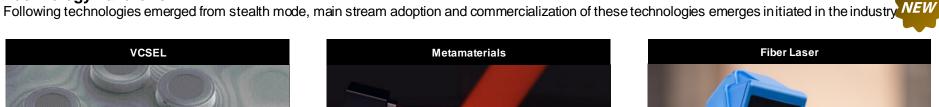


- Voy ant Photonics claims to reducing cost of LiDAR by more than 10 times
- The company in July 2019 raised \$4.3M from Contour Venture Partners, LDV Capital, and DARPA

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### **Technology Take-offs**









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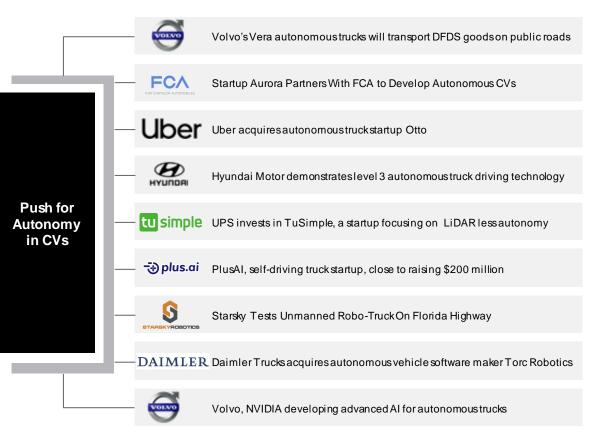




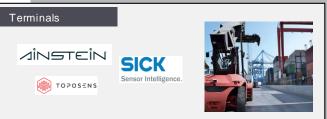
#### On the Road to Autonomous Trucks

Commercial Vehicles are also moving towards platooning and driverless through technology adoptions, collaboration, etc.









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## Regulatory / Standards Update

Most regulators are getting readied for standardizing autonomous vehicle testing and rolling out in early 2020s

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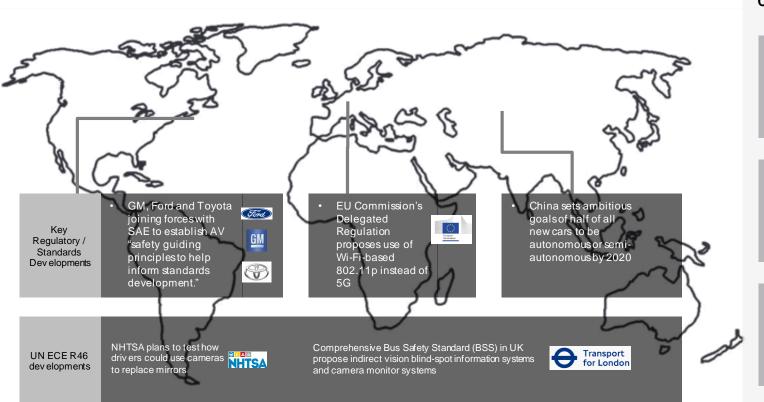
## Challenges in Regulating AV

IP Laws - Patenting activity in driverless vehicle technologies, could become a rat race where the largest firms race to patent every conceptual design

#### Lack of Standards / Guidelines -Regulators (e.g. in US) has shown

concern that the AV technology is yet to mature and will require more tests

Al as inventor? - Liability issues remains, related to Artificial Intelligence based application to account for liability / ownership



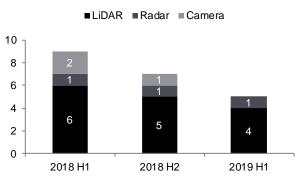
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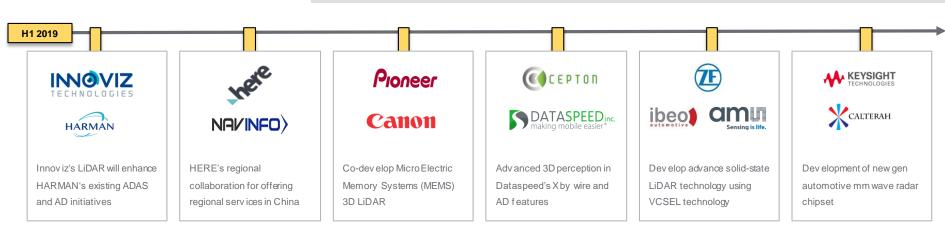
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#### **Collaboration Trends**

Breakthrough sub-technologies of vision system is being integrated through many collaborations



- Sensor manufacturers are collaborating with optics, beam steering experts for backward supply chain integrations, e.g. Pioneer & Canon | ZF & ams
- Also, sensor manufacturers are collaborating with ADAS & AD features providers, integrating with the forward supply chain
- Collaborations for localization services was also observed in H1 2019



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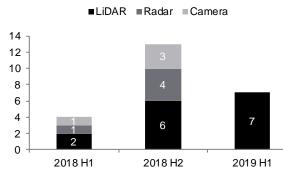
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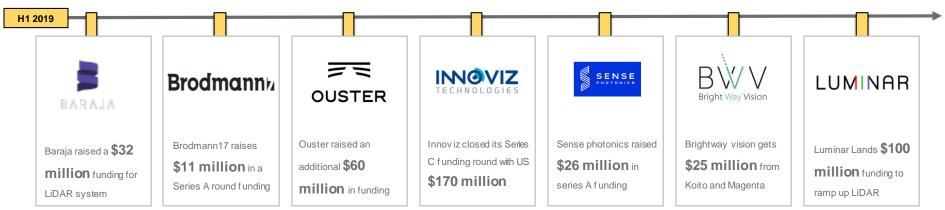


## **Funding Trends**

Breakthrough startups are getting more and more funds as part of larger industrial competition to pioneer autonomous technology



- Majority of funding activity concentrated on LiDAR and specifically on fiber laser based 3D sensing, e.g. Baraja and Luminar
- Investment from suppliers was also seen in new technologies (e.g. Bright Way Vision' Gated sensor technology)
  - Further, later rounds funding was aimed mass scale production Ouster and Luminar



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## IP Activity Summary

IP activity shows not only major OEMs and suppliers, but also new mobility entrants are actively filing patent in last one year time

#### IP activity (July 2018 to June 2019)

- Ford is leading sensing technology IP filing for last one year (in camera, LiDAR and radar)
- New mobility entrants like Waymo,
  Uber, etc. are also actively filing
  patent for vision sensors
- Lag of 18 months of patent publishing in public domain may be the reason for many vision sensor startups not showing up many patents
- Among suppliers Mobileye is leading while Bosch, Continental, Aptiv, etc. are also actively filing patents for vision system

Company	Camera	Lidar	Radar
Ford	191	138	79
INRIX	50	0	4
Mobileye	38	1	6
Volkswagen	16	0	0
GM	21	9	12
Mando	21	0	12
Bosch	15	0	6
JLR	12	3	6
Siemens	5	0	0
Continental	8	0	0
Peloton Technology	3	3	3
Waymo	5	30	18
Deepmap	13	24	0
TuSimple	14	9	0
Aptiv/Delphi	9	1	6
Koito	0	2	0
Uber	10	16	1
Denso	2	0	0

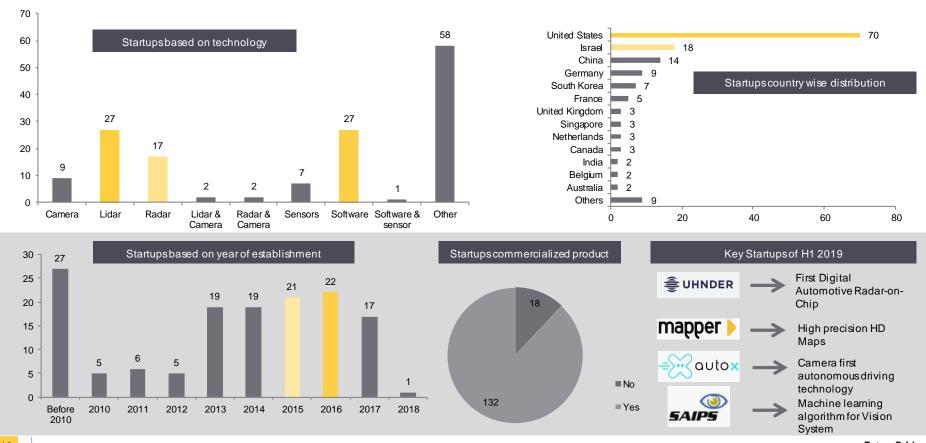
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## Startup Tracker Summary: H1'19

Vision sensor technology is being enhanced by companies for higher range, reliability, smaller size and lowering cost



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